

## Controller interface software Instruction

1. Insert the USB to RS485 convertor in one of your USB port
2. RUN "DRV\_CONF"
3. Set the baud rate to 38400
4. Click "Open port"
5. Set "Device Address" to 0 or 1
6. Enter Forward speed, like 50, then click Forward, the motor will run 50 rpm in forward direction
7. Enter reverse speed, like 100, then click Reverse, the motor will run 100 rpm in reverse direction
8. Click "Stop", the motor will stop running.